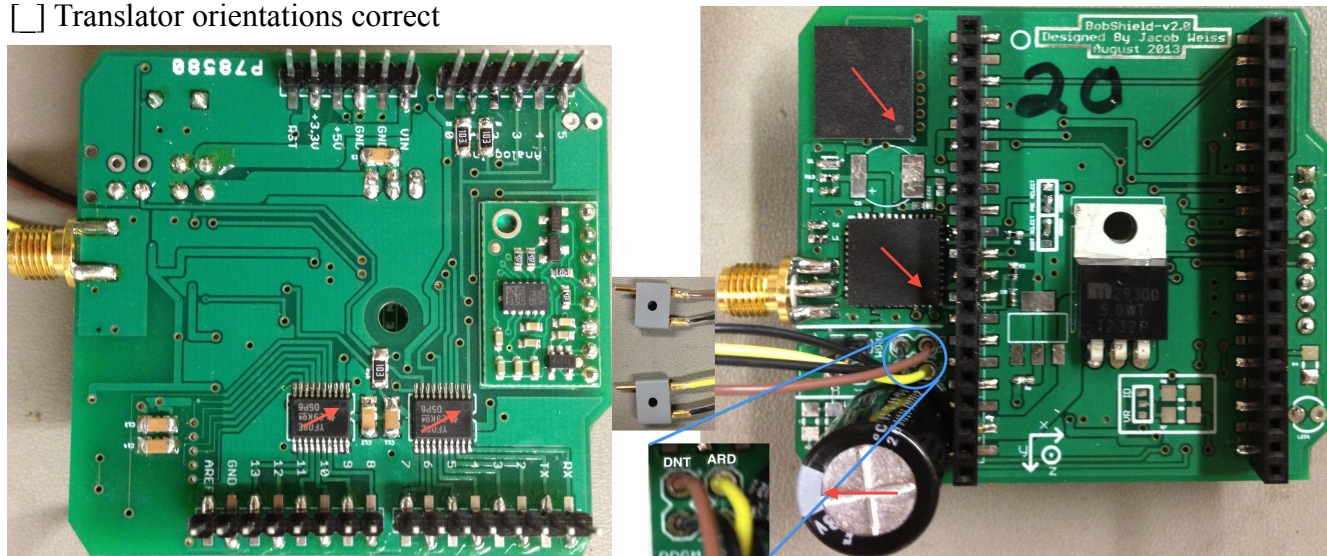


Shield Version ____ Shield Number ____ Battery Pack Number ____ Date ____/____/____

Arduino Label ____ DNT Label _____ Person Testing _____

Visual Inspection

- Flash oriented correctly
- GPS oriented correctly
- Power wires connected correctly
- Winchesters connected correctly
- Capacitor polarity correct
- Translator orientations correct



Power-Ground Separation

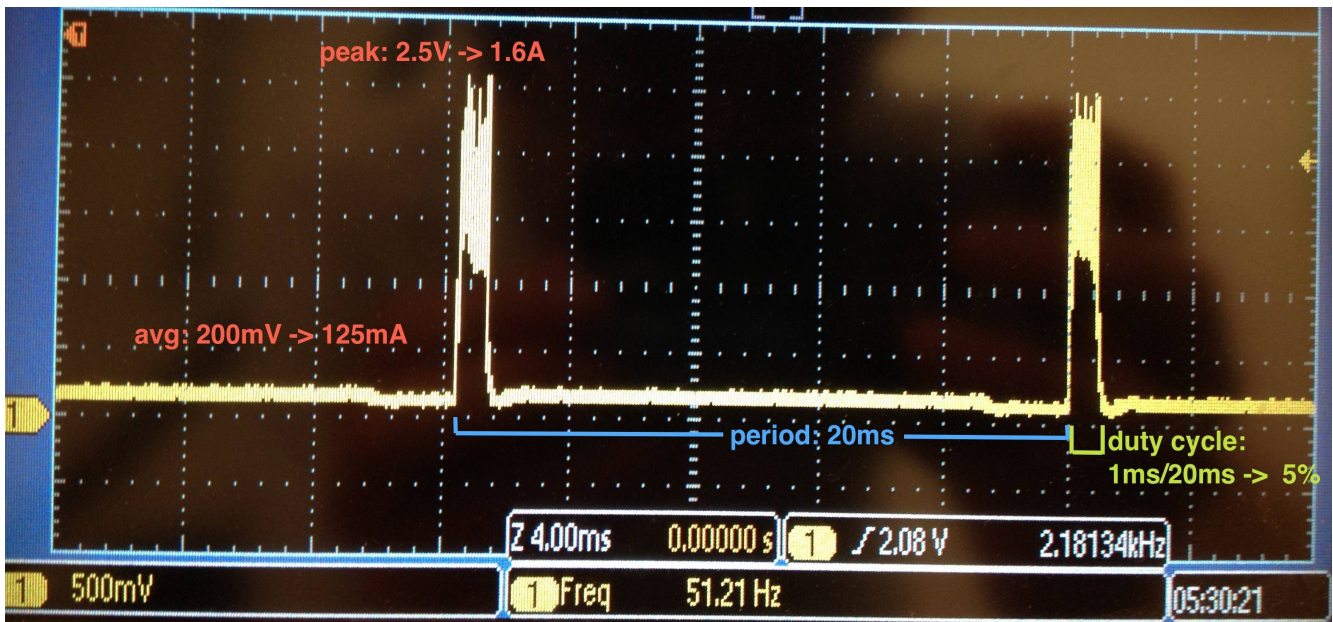
- Arduino and DNT battery grounds connected
- Arduino battery and Arduino board grounds connected
- Arduino and DNT battery positive leads not connected
- Arduino battery leads not connected
- DNT battery leads not connected
- GND and Arduino 5V not connected
- GND and Arduino 3.3V not connected
- GND and Arduino Vin not connected

Current Checks

- Connect the Arduino, shield, and DNT radio. Load ShieldTest1 onto the Arduino. Current of the Arduino powered alone _____ (should be ~ 50mA)

- Power both the DNT and Arduino and measure the DNT current draw.
 Receiving DNT data. No unexpected resets in the timestamp.
Baseline current _____ (should be ~ 150mA)
Peak current _____ (should be ~ 1,250mA)
Period of the peaks _____ (should be ~ 20ms)
Duty cycle _____ (should be ~ 5%)

Sketch →



Functionality Tests

- Load ShieldTest2 onto the Arduino. Connect PIP_OUT and PIP_IN. Run while collecting DNT data and rotating the device. Load BobDump onto the Arduino and collect the NAND data.
 - Good GPS data (realistic time and coordinates)
 - Good compass data
 - Accelerometer yields reasonable values and responds to rotating the payload
 - Magnetometer yields reasonable values and responds to rotating the payload
 - Analog pins OK
 - PIP_CTRL generates a response at PIP_OUT
 - PIP_IN accurately records this response when wired to PIP_OUT
 - NAND works
 - Can read/write data to the flash
 - Dumped data matches the DNT data reasonably well
- Load ShieldTest3 onto the Arduino. Send data to the Bob over the DNT radio
 - Bob receives DNT data
 - Response received for each message sent to the Bob
 - Response is not garbled